

## 6.3 Ecological Models

predator-prey system (Lotka-Volterra system)

$x(t)$ : prey (rabbits)

$y(t)$ : predator (wolves)      predator uses prey as food source

$$\frac{dx}{dt} = ax - pxy \quad a, b, p, g > 0$$

$$\frac{dy}{dt} = -by + gy$$

notice if there no predator,  $\frac{dx}{dt} = ax$  exponential growth

if there no prey,  $\frac{dy}{dt} = -by$  exponential decay

$$\frac{dx}{dt} = x(a - py) \quad \leftarrow \text{act as reduction to growth rate}$$

$$\frac{dy}{dt} = y(-b + gx) \quad \leftarrow \text{act as boost to growth rate}$$

$$\text{CP: } (0, 0), \left(\frac{b}{\delta}, \frac{a}{p}\right)$$

$$\text{Jacobian: } J(x, y) = \begin{bmatrix} a - py & -px \\ \delta y & -b + \delta x \end{bmatrix}$$

Goal: given  $x(0), y(0)$ , what happens to  $x(t), y(t)$  as  $t \rightarrow \infty$ ?

Example

$$\frac{dx}{dt} = x - 0.5xy = x(1 - 0.5y)$$

$$\frac{dy}{dt} = -0.75y + 0.25xy = y(-0.75 + 0.25x)$$

$$\text{CP: } (0, 0), (3, 2)$$

everybody  
dies

stable pop.

$$J(x, y) = \begin{bmatrix} 1 - 0.5y & -0.5x \\ 0.25y & -0.75 + 0.25x \end{bmatrix}$$

$$J(0, 0) = \begin{bmatrix} 1 & 0 \\ 0 & -0.75 \end{bmatrix}$$

$$\lambda = 1, -0.75$$

saddle

unstable

not sensitive to perturbation

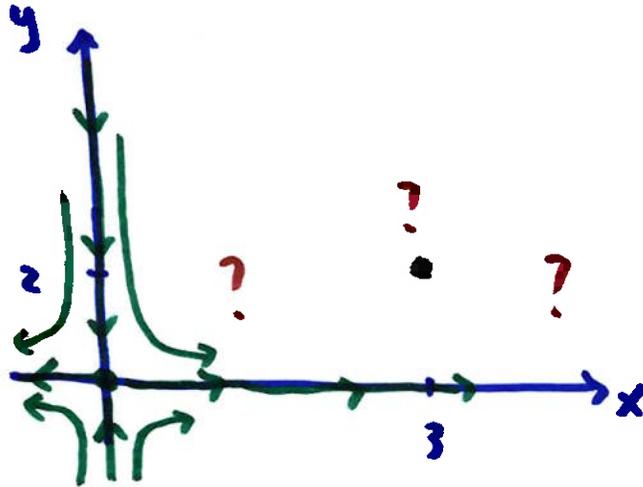
$$\vec{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Solutions near  $(0,0)$   $\vec{x}(t) = c_1 e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{-0.75t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

if initial condition leads to  $c_1 = 0$ ,

then  $\vec{x}(t) = c_2 e^{-0.75t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  into  $(0,0)$  along  $y$ -axis

likewise, we see solutions go away from  $(0,0)$  along  $x$ -axis



as long as  $x(0) \neq 0$

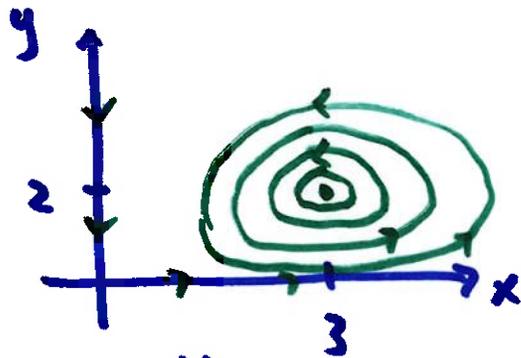
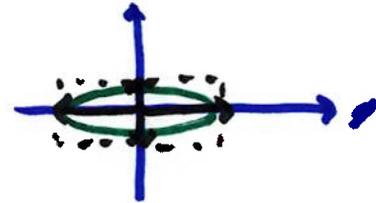
then solutions do NOT

go into  $(0,0)$

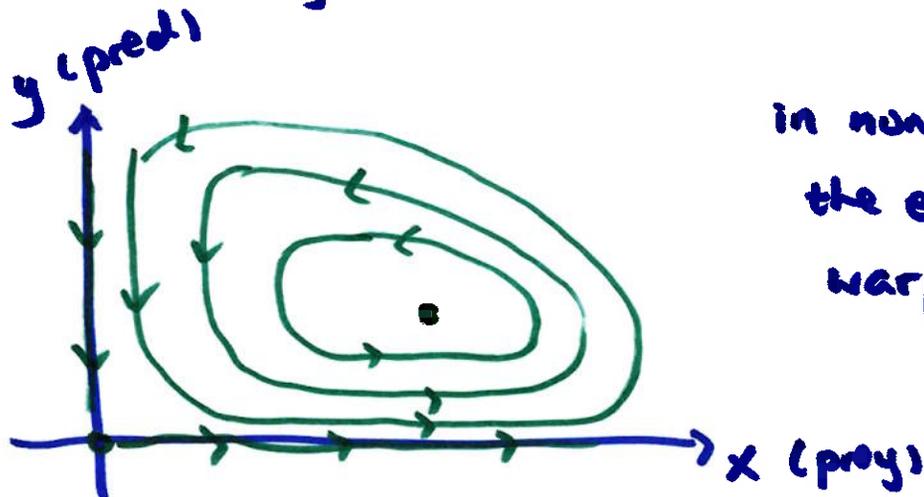
$$J(3, 2) = \begin{bmatrix} 0 & -1.5 \\ 0.5 & 0 \end{bmatrix} \quad \lambda = \pm \frac{\sqrt{3}}{2}i$$

center  
stable  
sensitive to perturbation  
(subject verification)

$$\vec{v} = \begin{bmatrix} 1 \\ \pm \frac{1}{\sqrt{3}}i \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \pm i \begin{bmatrix} 0 \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

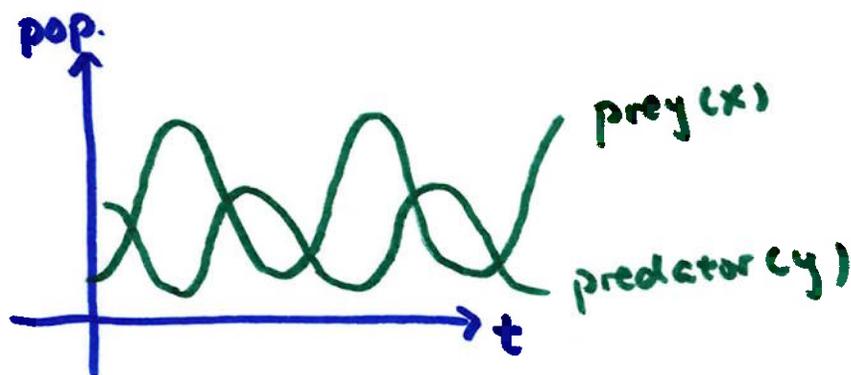


can use the flow from  
saddle pt to find direction  
of ellipse



in nonlinear picture  
the ellipses are generally  
warped.

x increases, then more food for y so it increases a bit later, then lots of y eating x so x declines, which means less food for y so y declines, so x has chance to increase and then the cycle repeats.



$$x' = ax - pxy$$

$$y' = -by + gxy$$

period of variation is  $\frac{2\pi}{\sqrt{ab}}$  independent of  $x(0), y(0)$

y lags behind x by a  $\frac{1}{4}$  period

amplitude of x is  $\frac{kb}{\delta}$

k: depends on  $x(0), y(0)$

" " y is  $\frac{k\sqrt{ab}}{p}$

verifying  $(3, 2)$  is a center: computer graph

or solve 
$$\left. \begin{aligned} x' &= ax - pxy \\ y' &= -by + gxy \end{aligned} \right\} \frac{dy}{dx} = \frac{y(-b+gx)}{x(a-px)}$$

$$\vdots$$
$$a \ln y - py + b \ln x - gx = C$$

warped ellipses.